First principles calculation of Solid-State NMR parameters

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Abstract

The past decade has seen significant advances in the technique of nuclear magnetic resonance as applied to condensed phase systems. This progress has been driven by the development of sophisticated radio-frequency pulse sequences to manipulate nuclear spins, and by the availability of high-field spectrometers. During this period it has become possible to predict the major NMR observables using periodic first-principles techniques. Such calculations are now widely used in the solid-state NMR community. In this short article we aim to provide an overview of the capability and challenges of solid-state NMR. We summarise the key NMR parameters and how they may be calculated from first principles. Finally we outline the advantages of a joint experimental and computational approach to solid-state NMR.

1 Introduction

Nuclear Magnetic Resonance (NMR) is, as the name implies, a spectroscopy of the nuclei in given material. Some nuclei (eg $^1$H, $^{13}$C, $^{29}$Si) are found to possess nuclear spin, and in the presence of a magnetic field exhibit small splittings in their nuclear spin states due to the Zeeman effect. Transitions between these levels are very much smaller than electronic excitations in the system and can be probed with radio-wave frequency pulses. At a first thought this might appear to only provide us with information about the nuclei; however, the precise splitting of the levels is found to be influenced by the surrounding electronic structure. This make NMR a highly sensitive probe of local atomic structure and dynamics.

For the case of a spin 1/2 nucleus the splitting is given by $E = -\gamma h B$ where $\gamma$ is the gyromagnetic ratio of the nucleus. To give a feel for the numbers involved we take the case of a hydrogen atom (for obvious reasons referred to as a proton by NMR spectroscopists) in the field of a typical NMR spectrometer (9.4 T). The separation of the nuclear spin levels is $2.65 \times 10^{-25}$ J. At room temperature the ratio of the occupancies of the upper and lower levels as given by Boltzmann statistics is 0.999935. This immediately tells us that NMR is a relatively insensitive technique: we could not hope to see the signal from a single site, rather we observe the signal from an ensemble of sites. With current techniques 10 micro-litres of sample could be sufficient in very favourable conditions, but often sample volumes are of the order of micro-litres. Sensitivity
The largest commercially available solid-state NMR spectrometers operate at a field of 23.5 T (giving a Larmor frequency for protons of 1 GHz). However, the nuclear constants are dictated by nature and some common isotopes such as $^{12}\text{C}$ or $^{16}\text{O}$ have no net spin, as will any nucleus with an even number of neutrons and protons. In many cases interesting and technologically significant elements have NMR active isotopes which are present in low abundance (eg Oxygen for which the NMR active $^{17}\text{O}$ is present at 0.037%) and/or have small $\gamma$ (eg $^{47}\text{Ti}$ which has $\gamma(^{47}\text{Ti})=0.06\gamma(^{1}\text{H})$). It is only with the latest techniques and spectrometers that NMR studies on such challenging nuclei has become feasible.

1.1 Solid-State NMR

After its initial development in the 1940’s NMR was rapidly adopted in the field of organic chemistry where is it now used as a routine analytic technique, illustrated by the fact that undergraduate students are taught to assign NMR spectra of organic compounds based on empirical rules. Advances in technique have enabled the study of protein structures and other complex bio-molecules. Given its application to such complex systems it may appear surprising that the use of NMR to study solid materials is still a developing research topic, and not yet a routine tool. To appreciate the difference between the solution state techniques of analytical chemistry and solid-state NMR it is important to understand that most interactions in NMR are anisotropic. In a simple way this means that the splitting of the nuclear spin states depend on the orientation of the sample with respect to the applied field. In solution, molecules tumble at a much faster rate than the Larmor frequency of the nuclei (which is typically between 50 and 1000 MHz). This means that nuclei will experience an average magnetic field, giving rise to a well defined transition frequency and sharp spectral lines. For a powdered solid the situation is different; instead of a time average we have an static average over all possible orientations. Rather than the sharp spectral lines observed in the solution-state a static NMR spectrum of a solid material will typically be a broad featureless distribution (see Figure 2). In a sense the problem is that NMR in the solid-state provides too much information. The experimentalist must work hard to remove the effects of these anisotropic interactions in order to obtain useful
Figure 2: Schematic Representation of the difference between NMR on liquids and powered solids. In a solution the molecules tumble, leading to averaging of anisotropic interactions and sharp spectral lines. In a powder the observed spectrum is now a superposition of all possible orientations, and anisotropic interactions lead to a broad spectrum.

information. On the other hand solid-state NMR has the potential to yield far more information than its solution-state counterpart. Anisotropic interactions can be selectively reintroduced into the experiment providing information on the principle components and orientations of the NMR tensors. The most widely used technique to reduce anisotropic broadening is Magic Angle Spinning (MAS). The magic angle, $\theta = 54.7^\circ$, is a root of the second-order Legendre polynomial $(3\cos^2(\theta) - 1)$. For a sample spun in a rotor inclined at a fixed angle to the magnetic field, it can be shown that the anisotropic component of most NMR tensors when averaged over one rotor period, have a contribution which depends on the second-order Legendre polynomial. It follows that if the sample is spun about $\theta = 54.7^\circ$ the anisotropic components will be averaged out (at least to first order). In practise this is achieved through the use of an air spin rotor, spinning speeds of 20kHz are common and the latest techniques allow for samples to be spun at up to 70kHz.

To summarise, a solid-state NMR spectrometer comprises of a superconducting magnet, encased in a large cooling bath (the part that is usually visible). A probe containing the sample is placed in a hole running though the centre of the magnet. The probe contains radio-frequency circuits to irradiate the sample, and also to collect the subsequent radio frequency emissions. In the case of solid-state NMR the probe also contains a device to rotate the sample. The probe may also be capable of heating or cooling the sample. Connected to the probe is a console which houses radio-frequency circuitry, amplifiers, digitisers and other pieces of electronics. To give some sample prices an ‘entry level’ 400MHz (9.4 T) solid-state NMR spectrometer would currently cost about 350,000 Euros, a more advanced spectrometer (600MHz 14.1 T) about 850,000 Euros, and the highest field spectrometers (1GHz 23.5 T) several millions of Euro.
2 NMR parameters

There are a large number of NMR experiments ranging in complexity from a simple (one-dimensional) spectrum of a spin one-half nucleus such as $^{13}$C, to sophisticated multidimensional spectra involving the transfer of magnetism between nuclear sites. All experiments depend on careful excitation, manipulation and detection of the nuclear spins. Several pieces of software have been developed to test NMR excitation sequences and to extract NMR parameters from experimental results (e.g. SIMPSON(2), Dmfit(3)). The correct language to describe this is that of effective nuclear Hamiltonians (see e.g. (4)). In a conceptual sense a spin Hamiltonian can be obtained from the full crystal Hamiltonian by integrating over all degrees of freedom except for the nuclear spins and external fields. The effect of the electrons and positions of the nuclei are now incorporated into a small number of tensor properties which define the key interactions in NMR. It is these tensors which can be obtained from electronic-structure calculations and we now examine them in turn.

2.1 Magnetic Shielding

The interaction between a magnetic field, $B$ and a spin 1/2 nucleus with spin angular momentum $\hbar I_K$ is given by

$$H = -\sum_K \gamma_K I_K \cdot B.$$

If we consider $B$ as the field at the nucleus due to presence of an externally applied field $B_{\text{ext}}$ we can express Eqn. 1 as

$$H = -\sum_K \gamma_K I_K (1 + \overline{\sigma}_K) B_{\text{ext}}.$$

The first term is the interaction of the bare nucleus with the applied field while the second accounts for the response of the electronic structure to the field. The electronic response is characterised by the magnetic shielding tensor $\overline{\sigma}_K$, which relates the induced field to the applied field

$$B_{\text{in}}(R_K) = -\overline{\sigma}_K B_{\text{ext}}.$$

In a diamagnet the induced field arises solely from orbital currents $j(r)$, induced by the applied field

$$B_{\text{in}}(r) = \frac{1}{c} \int d^3r' j(r') \times \frac{r - r'}{|r - r'|^3}.$$

The shielding tensor can equivalently be written as a second derivative of the electronic energy of the system

$$\overline{\sigma}_K = \frac{\partial^2 E}{\partial m_K \partial B}.$$

In solution state NMR, or for powdered solids under MAS conditions we are mainly concerned with the isotropic part of the shielding tensor $\sigma_{\text{iso}} = 1/3 Tr[\overline{\sigma}]$. The magnetic shielding results in nuclei in different chemical environments resonating at frequencies that are slightly different to the Larmor frequency of the bare nucleus. Rather than report directly the change in resonant frequency (which would depend of the magnetic field of the spectrometer) a normalised chemical shift is reported in parts per million (ppm)

$$\delta = \frac{\nu_{\text{sample}} - \nu_{\text{ref}}}{\nu_{\text{ref}}} (\times 10^6).$$
where \( \nu_{\text{ref}} \) is the resonance frequency of a standard reference sample. The magnetic shielding and chemical shift are related by

\[
\delta = \frac{\sigma_{\text{ref}} - \sigma_{\text{sample}}}{1 - \sigma_{\text{ref}}}. \tag{7}
\]

For all but very heavy elements \( |\sigma_{\text{ref}}| \ll 1 \) and so

\[
\delta = \sigma_{\text{ref}} - \sigma_{\text{sample}}. \tag{8}
\]

Figure 1 shows a typical \(^{13}\)C spectrum of a molecular crystal obtaining under MAS conditions. The spectrum consists of peaks at several different frequencies corresponding to carbon atoms in different chemical environments. The assignment has been provided by first-principles calculation of the magnetic shielding. Strategies for converting between calculated magnetic shielding and observed chemical shift have been discussed in Ref. (5).

Calculations of magnetic shieldings have been implemented in several local-orbitals quantum chemistry code; see Ref (6) for an overview. For crystalline systems the GIPAW approach for computing magnetic shieldings(7; 8) was initially implemented in the PARATEC code. This is no longer developed but implementations are available in the planewave pseudopotential codes CASTEP(9; 10) and Quantum-Espresso (11). A method using localised Wannier orbitals(12) has been implemented in the planewave CPMD code. The CP2K program has a recent implementation using the Gaussian and Augmented planewave method(13). In all these cases the shieldings are calculated using perturbation theory (linear response). Recently a method which avoids linear response, the so-called ‘converse approach’, have been developed (see Section3.2.2) and implemented in the Quantum-Espresso package.

### 2.2 Spin-spin coupling

In the previous section we considered the effect of the magnetic field at a nucleus resulting from an externally applied field. However, there may also be a contribution to the magnetic field at a nucleus arising from the magnetic moments of the other nuclei in the system. In an effective spin Hamiltonian we may associate this spin-spin coupling with a term of the form

\[
H = \sum_{K<L} I_K (D_{KL} + J_{KL}) I_L. \tag{9}
\]

\( D_{KL} \) is the direct dipolar coupling between the two nuclei and is a function of only the nuclear constants and the internuclear distance,

\[
D_{KL} = -\frac{\hbar}{2\pi \mu_0 4\pi \gamma_K \gamma_L} \frac{3r_{KL} r_{KL} - 1 r_L^2}{r_{KL}^5}. \tag{10}
\]

where \( r_{KL} = R_K - R_L \) with \( R_L \) the position of nucleus L. \( D_{KL} \) is a traceless tensor and its effects will be averaged out under MAS. However, dipolar coupling can be reintroduced to obtain information on spatial proximities of nuclei. \( J_{KL} \) is the indirect coupling and represents an interaction of nuclear spins mediated by the bonding electrons. \( J \) has an isotropic component and in solution-state NMR this leads to multiplet splitting of the resonances, see Figure 3. For light elements \( J \) is generally rather small (ie of the order of 100Hz for directly bonded carbon atoms, and often below 10Hz for atoms separated by more than one bond). This is less than the typical solid-state linewidth and so it is only with the very latest advances in experimental technique such as accurate setting of the magic angle, very high spinning speeds together with the
Figure 3: (a) Schematic representation of the effect of J coupling of two spin 1/2 nuclei on an NMR resonance. The peak is split by amount corresponding to the energy different between the spins being aligned parallel and antiparallel. (b) Schematic representation of the mechanism of transfer of J between nuclei. (c) Values of the J coupling (Hz) in Uracil ($^{1}$H- white, $^{13}$C - grey, $^{15}$N - blue, $^{17}$O - red)

availability of high-field spectrometers that is has become possible to measure small J couplings (see Ref.(14) for a recent summary). Highlights have included the observation of two J couplings between a given spin pair(15), the measurement of distributions of J in amorphous materials(16), and reports of J as low as 1.5Hz(17)

The J-coupling is a small perturbation to the electronic ground-state of the system and we can identify it as a derivative of the total energy $E$, of the system

$$J_{KL} = \frac{\hbar \gamma_K \gamma_L}{2\pi} \frac{\partial^2 E}{\partial \mathbf{m}_K \partial \mathbf{m}_L}$$

(11)

An equivalent expression arises from considering one nuclear spin (L) as perturbation which creates a magnetic field at a second (receiving) nucleus (K)

$$\mathbf{B}_{in}^{(1)}(\mathbf{r}_K) = \frac{2\pi}{\hbar \gamma_K \gamma_L} \mathbf{J}_{KL} \cdot \mathbf{m}_L.$$  

(12)

Eqn. 12 tells us that the question of computing J is essentially that of computing the magnetic field induced indirectly by a nuclear magnetic moment. The first complete analysis of this indirect coupling was provided by Ramsey(18; 19). When spin-orbit coupling is neglected we can consider the field as arising from two, essentially independent, mechanisms. Firstly, the magnetic moment can interact with electronic charge inducing an orbital current $j(r)$, which in turn creates a magnetic field at the other nuclei in the system. This mechanism is similar to the case of magnetic shielding in insulators. The second mechanism arises from the interaction of the magnetic moment with the electronic spin, causing an electronic spin polarisation. The relevant terms in the electronic Hamiltonian are the Fermi-contact (FC),

$$H_{FC} = g\beta \frac{\mu_0}{4\pi} \frac{8\pi}{3} \mathbf{S} \cdot \mathbf{\mu}_L \delta(\mathbf{r}_L),$$

(13)

and the spin-dipolar (SD),

$$H_{SD} = g\beta \frac{\mu_0}{4\pi} \mathbf{S} \cdot \left( \frac{3\mathbf{r}_L(\mathbf{\mu}_L \cdot \mathbf{r}_L) - r^2_\perp \mathbf{\mu}_L \mathbf{1}}{|\mathbf{r}_L|^5} \right).$$

(14)

Here $\mathbf{r}_L = \mathbf{r} - \mathbf{R}_L$ with $\mathbf{R}_L$ the position of nucleus L, $\mu_0$ is the permeability of a vacuum, $\delta$ is the Dirac delta function, $\mathbf{S}$ is the Pauli spin operator, $g$ the Lande g-factor and $\beta$ is the Bohr
magneton. The resulting spin density $m(r)$ creates a magnetic field through a second hyperfine interaction. By working to first order in these quantities we can write the magnetic field at atom K induced by the magnetic moment of atom L as

$$B^{(1)}_{\text{m}}(R_K) = \frac{\mu_0}{4\pi} \int m^{(1)}(r) \cdot \left[ \frac{3r_K r_K - |r_K|^2}{|r_K|^5} \right] d^3r$$

$$+ \frac{\mu_0}{4\pi} \frac{8\pi}{3} \int m^{(1)}(r) \delta(r_K) d^3r$$

$$+ \frac{\mu_0}{4\pi} \int j^{(1)}(r) \times \frac{r_K}{|r_K|^3} d^3r.$$ (15)

Several quantum chemistry packages provide the ability to compute J coupling tensors in molecular systems (see Ref. (20) for a review of methods). An approach to compute J tensors within the planewave-pseudopotential approach has recently been developed(21). Some examples are discussed in Section 4.3, and a review of applications is provided in Ref. (22).

### 2.3 Electric Field Gradients

For a nucleus with spin $>1/2$ the NMR response will include an interaction between the quadrupole moment of the nucleus, Q, and the electric field gradient (EFG) generated by the surrounding electronic structure. The EFG is a second rank, symmetric, traceless tensor $G(r)$ given by

$$G_{\alpha\beta}(r) = \frac{\partial E_{\alpha}(r)}{\partial r_{\beta}} - \frac{1}{3} \delta_{\alpha\beta} \sum_{\gamma} \frac{\partial E_{\gamma}(r)}{\partial r_{\gamma}}$$ (16)

where $\alpha, \beta, \gamma$ denote the Cartesian coordinates $x,y,z$ and $E_{\alpha}(r)$ is the local electric field at the position $r$, which can be calculated from the charge density $n(r)$:

$$E_{\alpha}(r) = \int d^3r \frac{n(r)}{|r - r'|^3} (r_{\alpha} - r'_{\alpha}).$$ (17)

The EFG tensor is then equal to

$$G_{\alpha\beta}(r) = \int d^3r \frac{n(r)}{|r - r'|^3} \left[ \delta_{\alpha\beta} - \frac{(r_{\alpha} - r'_{\alpha})(r_{\beta} - r'_{\beta})}{|r - r'|^2} \right].$$ (18)
The computation of electric field gradient tensors is less demanding than either shielding or J-coupling tensors as it requires only knowledge of the electronic ground state. The LAPW approach in its implementation within the Wien series of codes(24) has been widely used and shown to reliably predict Electric Field Gradient (EFG) tensors(25). The equivalent formalism for the planewave/PAW approach is reported in Ref. (26).

The quadrupolar coupling constant, $C_Q$ and the asymmetry parameter, $\eta_Q$ can be obtained from the the diagonalized electric field gradient tensor whose eigenvalues are labelled $V_{xx}$, $V_{yy}$, $V_{zz}$, such that $|V_{zz}| > |V_{yy}| > |V_{xx}|$:

$$C_Q = \frac{eV_{zz}}{h},$$

where $h$ is Planck's constant and

$$\eta_Q = \frac{V_{xx} - V_{yy}}{V_{zz}}.$$  (20)

The effect of quadrupolar coupling is not completely removed under MAS, leading to lineshapes which can be very broad. Figure 4 shows a typical MAS spectrum for a spin 3/2 nucleus. The width of each peak is related to $C_Q$ and the shape to $\eta_Q$. See Ref. (27) for recent review of NMR techniques for quadrupolar nuclei.

### 2.4 Paramagnetic Coupling

If a material contains an unpaired electron then this net electronic spin can create an additional magnetic field at a nucleus via Fermi contact and spin-dipolar mechanisms. Paramagnetism introduces several difficulties from the point of view of solid-state NMR, for example the resonances can exhibit significant broadening. However, NMR has been used to analyse local magnetic interactions, for example in manganites(28) and lithium battery materials(29). There are several reports of calculations of NMR parameters in paramagnetic systems for example paramagnetic shifts of $^6$Li(30) and EFGs of layered vanadium phosphates(31). However, to the best of our knowledge, unlike the case of paramagnetic molecules(32) there is currently no methodology to predict all of the relevant interactions in paramagnetic solids at a consistent computational level.

In metallic systems the electronic spin also plays an important role as the external field will create a net spin density (Pauli susceptibility) which will in turn create a magnetic field at the nucleus. This additional contribution to the magnetic shielding is known as the Knight shift. The linear-response GIPAW approach has been extended(33) to compute the magnetic shielding and Knight-shift in metallic systems, although there have been few applications to date.

### 3 A first principles approach

In order to have a scheme for computing solid-state NMR properties with the planewave-pseudopotential implementation of DFT there are two major challenges. Firstly, how to deal with the fact that the pseudo-wavefunction does not have the correct nodal structure in the region of interest, ie the nucleus. Secondly, how to compute the response of the system to an applied field. We examine these in turn.
The combination of pseudopotentials and a planewave basis has proved to give a reliable description of many material properties, such as vibrational spectra and dielectric response (10; 34), but properties which depend critically on the wavefunction close to the nucleus, such as NMR tensors require careful treatment. The now standard approach to computing such properties is the projector augmented wave method (PAW) introduced by Blöchl (35) which provides a formalism to reconstruct the all-electron wavefunction from its pseudo counterpart, and hence obtain all-electron properties from calculations based on the use of pseudopotentials.

The PAW scheme proposes a linear transformation from the pseudo-wavefunction $|\tilde{\Psi}\rangle$, to the true all-electron wavefunction $|\Psi\rangle$, i.e. $|\Psi\rangle = T|\tilde{\Psi}\rangle$, where

$$T = 1 + \sum_{R,n} \left( |\phi_{R,n}\rangle - |\tilde{\phi}_{R,n}\rangle \right) \langle \tilde{\phi}_{R,n} | \langle \phi_{R,n} |$$

(21)

$|\phi_{R,n}\rangle$ is a localised atomic state (say 3p) and $|\tilde{\phi}_{R,n}\rangle$ is its pseudized counterpart. $|\tilde{\phi}_{R,n}\rangle$ are a set of functions which project out the atomic like contributions from $|\tilde{\Psi}\rangle$. This equation is represented pictorially in Figure 5. For an all-electron local or semi-local operator $O$, the corresponding pseudo-operator, $\tilde{O}$, is given by

$$\tilde{O} = O + \sum_{R,n,m} |\tilde{\phi}_{R,n}\rangle \left( \langle \phi_{R,n} | O | \phi_{R,m} \rangle - \langle \tilde{\phi}_{R,n} | O | \tilde{\phi}_{R,m} \rangle \right) \langle \tilde{\phi}_{R,m} |$$

(22)
As constructed in Eqn. 22 the pseudo-operator $\tilde{O}$ acting on pseudo-wavefunctions will give the same matrix elements as the all-electron operator $O$ acting on all-electron wavefunctions. Pseudo operators for the operators relevant for magnetic shielding are reported in Ref. (7; 8), for electric field gradients in Ref. (26) and for J coupling in Ref. (21). Pseudo-operators for magnetic shielding including relativistic effects at the ZORA level are given in Ref. (36)

For a system under a uniform magnetic field PAW alone is not a computationally realistic solution. In a uniform magnetic field a rigid translation of all the atoms in the system by a vector $t$ causes the wavefunctions to pick up an additional field dependent phase factor, which can we written as, using the symmetric gauge for the vector potential, $A(r) = \frac{1}{2}\mathbf{B} \times \mathbf{r}$,

$$\langle \mathbf{r} | \Psi'_n \rangle = e^{\frac{i}{2c} \mathbf{r} \cdot \mathbf{t} \times \mathbf{B}} \langle \mathbf{r} - \mathbf{t} | \Psi_n \rangle. \tag{23}$$

In short Eqn. 22 will require a large number of projectors to describe the oscillations in the wavefunctions due to this phase. In using a set of localized functions we have introduced the gauge-origin problem well known in quantum chemical calculations of magnetic shieldings(6). To address this problem Pickard and Mauri introduced a field dependent transformation operator $T_B$, which, by construction, imposes the translational invariance exactly:

$$T_B = 1 + \sum_{R,n} e^{\frac{i}{2c} \mathbf{r} \cdot \mathbf{R} \times \mathbf{B}} \langle \phi_{R,n} | - | \tilde{\phi}_{R,n} \rangle \langle \tilde{\phi}_{R,n} | e^{-\frac{i}{2c} \mathbf{r} \cdot \mathbf{R} \times \mathbf{B}}. \tag{24}$$

The resulting approach is known as the Gauge Including Projector Augmented Wave (GIPAW) method.

(GI)PAW techniques allow us to reconstruct the valence wavefunction in the core region, however the pseudopotential approach is usually coupled with a frozen-core approximation. A careful study of all-electron calculations on small molecules(37) has shown that this is a valid approximation for the calculation of magnetic shielding; the contribution of the core electrons to the magnetic shielding is not chemically sensitive and can be computed from a calculation on a free atom. Figure 6 shows shieldings computed using pseudopotentials and the GIPAW scheme, together with large Gaussian basis-set quantum-chemical calculations. For shieldings in these isolated molecules the agreement is essentially perfect. However, in practise it is not always straightforward to partition states into core and valence. This is highlighted by the calculation of electric field gradients in 3d and 4d elements such as V and Nb. Here a major contribution to the electric field gradient arises from the small distortion of the highest occupied p states, and it is essential to include these states as valence for accurate NMR parameters (2p for V, 3p for Nb). The use of ultrasoft potentials has proved to be essential to constructing efficient pseudopotentials with these semi-core state in valence. Figure 6 shows the comparison of pseudopotential+PAW calculations with those using the Wien2k code(38). The agreement between the two approaches is very good. Other examples include the study of $^{95}$Mo NMR parameters.(39)
Figure 6: Comparison of all-electron and pseudopotential (with frozen core) calculations of NMR parameters. (a) Comparison of chemical shieldings for a range of small molecules computed using Guassian basis sets and those from pseudopotential calculations without the GIPAW augmentation (b) as previous but using the GIPAW augmentation (c) Comparison of $^{93}$Nb Quadrupolar Couplings computed using pseudopotentials and PAW with results from an LAPW+lo code (d) Results from previous as compared to experiment.

3.2 Magnetic Response

3.2.1 Linear Response

As discussed in Section 2 one route to obtaining the magnetic shielding is to compute the induced orbital current, $j^{(1)}(\mathbf{r})$ using perturbation theory,

$$ j^{(1)}(\mathbf{r'}) = 4 \sum_o \text{Re} \left[ \langle \Psi^{(0)}_o | \mathbf{J}^p(\mathbf{r'}) | \Psi^{(1)}_o \rangle \right] + 2 \sum_o \langle \Psi^{(0)}_o | \mathbf{J}^d(\mathbf{r'}) | \Psi^{(0)}_o \rangle. $$

(25)

The current operator, $\mathbf{J}(\mathbf{r'})$ is obtained from the quantum mechanical probability current, replacing linear with canonical momentum. It can be written as the sum of diamagnetic and paramagnetic terms,

$$ \mathbf{J}(\mathbf{r'}) = \mathbf{J}^d(\mathbf{r'}) + \mathbf{J}^p(\mathbf{r'}), $$

(26)

$$ \mathbf{J}^d(\mathbf{r'}) = \frac{1}{c} \mathbf{A}(\mathbf{r'}) |\mathbf{r'}\rangle \langle \mathbf{r'}|, $$

(27)

$$ \mathbf{J}^p(\mathbf{r'}) = \frac{\mathbf{p}|\mathbf{r'}\rangle \langle \mathbf{r'}| + |\mathbf{r'}\rangle \langle \mathbf{r'}| \mathbf{p}}{2}. $$

(28)
The first-order change in the wavefunction $|\Psi_o^{(1)}\rangle$, is given by

$$|\Psi_o^{(1)}\rangle = \sum_e \frac{|\Psi_o^{(0)}\rangle\langle \Phi_r^e|}{\varepsilon - \varepsilon_e} H^{(1)}|\Psi_o^{(0)}\rangle = G(\varepsilon_o^{(0)})H^{(1)}|\Psi_o^{(0)}\rangle,$$

(29)

where $H^{(1)} = \mathbf{p} \cdot \mathbf{A} + \mathbf{A} \cdot \mathbf{p}$. Using the symmetric gauge for the vector potential, $\mathbf{A}(\mathbf{r}) = (1/2)\mathbf{B} \times \mathbf{r}$, we arrive at the following expression for the induced current,

$$j^{(1)}(\mathbf{r}') = 4 \sum_o \text{Re} \left[ \langle \Psi_o^{(0)} | \mathbf{J}^p(\mathbf{r}')G(\varepsilon_o^{(0)})\mathbf{r} \times \mathbf{p} | \Psi_o^{(0)} \rangle \right] - \frac{1}{2c} \rho(\mathbf{r}')\mathbf{B} \times \mathbf{r}'$$

(30)

In an insulator the Green function $G(\varepsilon_o^{(0)})$ is localized and so $j^{(1)}(\mathbf{r}')$ remains finite at large values of $|\mathbf{r} - \mathbf{r}'|$. At this point there still remains the question of the practical computation of the current, which for reasons of efficiency it is desirable to work with just the cell periodic part of the Bloch function. Eqn. 31 is not suitable for such a calculation as the position operator cannot be expressed as a cell periodic function. One solution to this problem is to consider the induced current defined. Through the use of a sum-rule we arrive at an alternative expression for the current

$$j^{(1)}(\mathbf{r}') = 4 \sum_o \text{Re} \left[ \langle \Psi_o^{(0)} | \mathbf{J}^p(\mathbf{r}')G(\varepsilon_o^{(0)})(\mathbf{r} - \mathbf{r}') \times \mathbf{p} | \Psi_o^{(0)} \rangle \right].$$

(31)

In an insulator the Green function $G(\varepsilon_o^{(0)})$ is localized and so $j^{(1)}(\mathbf{r}')$ remains finite at large values of $(\mathbf{r} - \mathbf{r}')$. At this point there still remains the question of the practical computation of the current, which for reasons of efficiency it is desirable to work with just the cell periodic part of the Bloch function. Eqn. 31 is not suitable for such a calculation as the position operator cannot be expressed as a cell periodic function. One solution to this problem is to consider the response to a magnetic field with a finite wavelength i.e. $\mathbf{B} = \sin(\mathbf{q} \cdot \mathbf{r})\mathbf{q}$. In the limit that $q \to 0$ the uniform field result is recovered. For a practical calculation this enables one to work with cell periodic functions, at the cost that a calculation at a point in the Brillouin Zone $\mathbf{k}$ will require knowledge of the wavefunctions at $\mathbf{k} \pm \mathbf{q}$ (ie six extra calculations for the full tensors for all atomic sites). A complete derivation was presented in Refs. (7; 40) leading to the final result for the current,

$$j^{(1)}(\mathbf{r}') = \lim_{q \to 0} \frac{1}{2q} \left[ \mathbf{S}(\mathbf{r}', q) - \mathbf{S}(\mathbf{r}', -q) \right]$$

(32)

where

$$\mathbf{S}(\mathbf{r}', q) = \frac{2}{cN_k} \sum_{i=x,y,z} \sum_{o,k} \sum_{p} \text{Re} \left[ \frac{1}{i} \langle \phi_{o,k}^{(0)} | \mathbf{J}_{k,k+q_i}^p(\mathbf{r}')G_{k+q_i}(\varepsilon_o^{(0)})\mathbf{B} \times \hat{\mathbf{u}}_i \cdot (\mathbf{p} + \mathbf{k})\phi_{o,k}^{(0)} \rangle \right],$$

$q_i = q\hat{\mathbf{u}}_i$, $N_k$ is the number of $\mathbf{k}$-points included in the summation and

$$\mathbf{J}_{k,k+q_i}^p = -\frac{(\mathbf{p} + \mathbf{k})|\mathbf{r}'| + |\mathbf{r}'|(\mathbf{p} + \mathbf{k} + \mathbf{q}_i)}{2}.$$

Equivalent expressions valid when using separable norm-conserving pseudopotentials are given in Ref. (7), and for ultrasoft potentials in Ref. (8).

### 3.2.2 Converse Approach

The problem of computing NMR shielding tensors can be reformulated so that the need for a linear-response framework is circumvented. In this way the NMR shifts are obtained from
the macroscopic magnetization induced by magnetic point dipoles placed at the nuclear sites of interest. This method shall be referred to as converse (41; 42) as opposed to direct approaches, based on linear-response, in which a magnetic field is applied and the induced field at the nucleus is computed.

The converse approach is made possible by the recent developments that have led to the Modern Theory of Orbital Magnetization (43–47), which provides an explicit quantum-mechanical expression for the orbital magnetization of periodic systems in terms of the Bloch wave functions and Hamiltonian, in absence of any external magnetic field.

The converse and linear response approaches should give the same shielding tensors if the same electronic structure method is used (eg the LDA). The main advantage of the converse approach is that it can be coupled easily to advanced electronic structure methods and situations where a linear-response formulation is cumbersome or unfeasible. For example in the case of DFT+U (48) or hybrid functionals, the converse method should provide a convenient shortcut from the point of view of program coding. It is possible that in the case of high-level correlated approaches like multi-configuration (49; 50) and quantum Monte Carlo, the converse method will also provide a convenient route to calculate NMR chemical shifts.

Let us start by considering a sample to which a constant external magnetic field $B_{\text{ext}}$ is applied. The field induces a current that, in turn, induces a magnetic field $B_{\text{ind}}(r)$ such that the total magnetic field is $B(r) = B_{\text{ext}} + B_{\text{ind}}(r)$. In NMR experiments the applied fields are small compared to the typical electronic scales; the absolute chemical shielding tensor $\vec{\sigma}$ is then defined via the linear relationship

$$\delta_{\alpha\beta} - \sigma_{s,\alpha\beta} = -\frac{\partial E}{\partial m_{s,\beta}}.$$

(34)

The index $s$ indicates that the corresponding quantity is to be taken at position $r_s$, i.e., the site of nucleus $s$.

Instead of determining the current response to a magnetic field, we derive chemical shifts from the orbital magnetization induced by a magnetic dipole. Using $B_{s,\alpha} = B_{\text{ext}}^{\alpha} + B_{\text{ind}}^{\alpha}$, Eq. (34) becomes $\delta_{\alpha\beta} - \sigma_{s,\alpha\beta} = \partial B_{s,\alpha}/\partial B_{\beta}$. The numerator may be written as $B_{s,\alpha} = -\partial E/\partial m_{s,\alpha}$, where $E$ is the energy of a virtual magnetic dipole $m_s$ at the nuclear position $r_s$ in the field $B$. Then, writing the macroscopic magnetization as $M_{\beta} = -\Omega^{-1} \partial E/\partial B_{\beta}$ (where $\Omega$ is the cell volume), we obtain

$$\delta_{\alpha\beta} - \sigma_{s,\alpha\beta} = -\frac{\partial}{\partial B_{\beta}} \frac{\partial E}{\partial m_{s,\alpha}} = -\frac{\partial}{\partial m_{s,\alpha}} \frac{\partial E}{\partial B_{\beta}} = \Omega \frac{\partial M_{\beta}}{\partial m_{s,\alpha}}.$$

(35)

Thus, $\vec{\sigma}_s$ accounts for the shielding contribution to the macroscopic magnetization induced by a magnetic point dipole $m_s$ sitting at nucleus $r_s$ and all of its periodic replicas. In other words, instead of applying a constant (or long-wavelength) field $B_{\text{ext}}$ to an infinite periodic system and calculating the induced field at all equivalent nuclei $s$, we apply an infinite array of magnetic dipoles to all equivalent sites $s$ and calculate the change in orbital magnetization (47). Since the perturbation is now periodic, it can easily be computed using finite differences of ground-state calculations. Note that $M = m_s/\Omega + M_{\text{ind}}$, where the first term is present merely because we have included magnetic dipoles by hand. It follows that the shielding is related to the true induced magnetization via $\sigma_{s,\alpha\beta} = -\Omega \partial M_{\text{ind}}^{\beta}/\partial m_{s,\alpha}$. 

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In order to calculate the shielding tensor of nucleus $s$ using eq. (35), it is necessary to calculate the induced orbital magnetization due to the presence of an array of point magnetic dipoles $m_s$ at all equivalent sites $r_s$. The vector potential of a single dipole in Gaussian units is given by

$$A_s(r) = \frac{m_s \times (r - r_s)}{|r - r_s|^3} \quad (36)$$

For an array of magnetic dipoles $A(r) = \sum_R A_s(r - R)$, where $R$ is a lattice vector. Since $A$ is periodic, the average of its magnetic field $\nabla \times A$ over the unit cell vanishes; thus, the eigenstates of the Hamiltonian remain Bloch-representable. The periodic vector potential $A(r)$ can now be included in the Hamiltonian with the usual substitution for the momentum operator $p \rightarrow p - e\mathbf{c}A$, where $m_e$ is the electronic mass and $c$ is the speed of light. Because of the lattice periodicity of the vector potential, the magnetic dipole interacts with all its images in neighboring cells. However, due to the $1/r^3$ decay of the dipole-dipole interaction, the chemical shifts are found to converge very fast with respect to super-cell size.

In practice, we can calculate the full shielding tensor by performing three SCF ground state calculations. In each SCF calculation, we place a virtual magnetic dipole $m_s$ (eq. (36)) aligned along one of the Cartesian directions and we calculate the resulting change in orbital magnetization.

The main disadvantage of the converse method is requires a set of three calculations for every atom we are interested in, as opposed to linear-response, which yield all the shielding tensors at once. This disadvantage can be partly mitigated by distributing every set of calculations on a large number of CPUs and machines. Of course, if we are interested on in a subset of atomic sites or atomic species, the converse method can be efficient as the linear-response approach.

In the case of a pseudopotential code the situation is complicated due to nonlocal projectors usually used in the Kleinman-Bylander separable form. However, by using the GIPAW formalism, the converse method has recently been generalized such that it can be used in conjunction with norm-conserving, non-local pseudopotentials, to calculate the NMR chemical shifts (51) and the EPR g-tensor (52).

The converse method has been recently implemented in Quantum-Espresso (11), VASP (53) and ADF-BAND (54).

4 Uses of Computations

4.1 NMR Crystallography

Diffraction based techniques are the traditional route to obtaining information on the structure of crystalline solids. Diffraction certainly provides information on long-range order and atomic positions. However, it is less sensitive to local disorder whether that be positional or compositional. In systems such as microporous framework materials (layered hydroxides, zeolites) this local disorder plays a key role in determining the macroscopic physico-chemical properties. As solid-state NMR is a local probe it can be used to provide insight on such local defects as a complement to the information provided by diffraction. Moving to amorphous materials, while diffraction studies provide information on first-nearest neighbour distributions, NMR can provide complimentary information about second nearest neighbours and hence bond angles. In
many supramolecular systems and organic compounds it is often not possible to obtain large single crystals. In such cases diffraction studies often provide only limited information e.g. just the unit cell parameters. However, the corresponding solid-state NMR spectra can show sharp peaks demonstrating that the material is locally well ordered. Here the challenge is to go directly from NMR data to the crystal structure. NMR can also be used to probe dynamics in crystalline materials; a range of NMR experiments can be used to examine motion on different timescales(55). In all cases the ability to compute NMR observables from first-principles essential in order to provide the link between structure and spectra.

We examine some recent studies which highlight the interplay between diffraction, solid-state NMR and computations. An extensive list of applications of plane-wave/pseudopotential calculations of NMR parameters can be found at http://www.gipaw.net.

4.1.1 Clinohumite - local disorder

![Figure 7](image)

Figure 7: (a) Crystal structure of Clinohumite showing the staggered arrangement of F/OH sites (grey). Atom colours are: Si (blue), Mg (green), O(red). (b) $^{19}$F MAS NMR spectrum of 50% fluorinated clinohumite. (c) Four possible local fluorine environments (d) Comparison of calculated $^{19}$F shielding and experimental shifts.

First-principles calculations and solid-state NMR have recently been used to study disorder in the fluorine substituted hydrous magnesium silicate clinohumite ($4\text{Mg}_2\text{SiO}_4\cdot\text{Mg(F,OH)}_2$). This mineral is of considerable interest as model for the incorporation of water within the Earth’s upper mantle. Diffraction provides the overall crystal structure but gives no information on the ordering of the $F^-/OH^-$ ions. As shown in Figure 7 the $^{19}$F NMR spectrum reveals 4 distinct fluorine environments. Griffin et al performed first-principles calculations(56) on a series of supercells of clinohumite using F and OH substitutions to generate all possible local fluorine
environments. From these it was found that the computed $^{19}\text{F}$ NMR parameters were clustered into four distinct ranges depending on their immediate neighbours. The ranges correspond well to the observed peaks providing an assignment of the spectrum. Interestingly further experiments revealed the presence of $^{19}\text{F}-^{19}\text{F}$ J-couplings despite the fact that there is no formal bond between fluorine atoms. The magnitude of these coupling was reproduced by first-principles calculations, suggesting that there is a ‘though-space’ component to these J-couplings.

4.1.2 Ge$_x$Se$_{1-x}$ glasses

![Diagram](image)

Figure 8: Average (vertical lines) and range (horizontal lines) of $^{77}\text{Se}$ chemical shifts as found for various Se sites in several crystalline precursors of Germanium Selenide glasses, together with experimental $^{77}\text{Se}$ MAS spectra for Ge$_x$Se$_{1-x}$ glasses.

Conventional diffraction studies do not provide sufficient information to determine the short range order in Chalcogenide Ge$_x$Se$_{1-x}$ glasses, which can include corner-sharing, and edge-sharing, tetrahedral arrangements, under-coordinated and over-coordinated atoms, and homopolar bonds. Recent $^{77}\text{Se}$ NMR studies obtained under MAS have shown two large, but rather broad peaks (as shown in Figure 8). Two conflicting interpretations have been suggested: the first consists of a model of two weakly linked phases, one characterised by Se-Se-Se sites, the other Se-Ge-Se. The second model assumes a fully bonded structure with the contributions from Ge-Se-Se and Ge-Se-Ge linkages overlapping. To answer this question Kibalchenko et al. (57) carried out first-principles calculations on several crystalline precursors of Germanium Selenide glasses (GeSe$_2$, Ge$_4$Se$_9$ and GeSe) to establish the range of chemical shifts associated with each type of Se site. The results are summarised in Figure 8. This connection between local structure and observed NMR parameters provides a reliable interpretation of the $^{77}\text{Se}$ spectra of Ge$_x$Se$_{1-x}$ glasses, ruling out the presence of a bimodal phase and supporting a fully bonded structure.
Charpentier and co-workers have used a combination of Monte Carlo and molecular dynamics simulations together with first-principles calculations of NMR parameters in order to parameterise the relationship between local atomic structure and NMR observables. This methodology has been applied to interpret the NMR spectra of several amorphous materials including vitreous silica(58), calcium silicate glasses(59), lithium and sodium tetrasilicate glasses(60).

4.1.3 Structure Solution

A challenge for solid-state NMR is the idea of ‘NMR Crystallography’: the ability to go directly from an observed NMR spectrum to the crystal structure(61). Early work by Facelli and Grant(62) combined calculation of $^{13}$C magnetic shieldings with single crystal NMR studies. More recently proton-proton spin diffusion (PSD) experiments have been shown to provide three dimensional crystal structures which can be successfully used as input into a scheme for crystal structure determination. In Ref. (63) PSD measurements were combined with subsequent DFT geometry optimisations to give the crystal structure of the small molecule thymol in good agreement with diffraction data. There has been considerable effort to develop schemes based on molecular modelling to predict the lowest energy polymorphs of molecular crystals. At the present time the best schemes are able to reliably predict the naturally occurring structure amongst a set of 10-100 low energy structures. Recent work has shown that the combination of computational and experimental $^1$H chemical shifts is sufficient to identify the experimental structure from amongst this set of candidate structures(64).

4.2 Dynamics and the role of temperature

NMR can be used to study motional processes in solids. One technique is the use of deuterium NMR. $^2$H has spin I=2 and the magnitude of its quadrupolar coupling (typically 250kHz) makes it suitable to study motional processes on the micro and millisecond timescale. Griffin et al(65) have used $^2$H solid-state NMR to study the dynamic disorder of hydroxyl groups in hydroxyl-clinohumite. In this material the deuteron can exchange between two crystallographic sites. By combining first-principles calculations, a simple model of the effect of motion on the NMR line-broadening, and experimental $^2$H NMR spectra it was possible to obtain the activation energy for the exchange processes.

NMR spectra are commonly obtained at room temperature. Given that first-principles calculations are typically use a static configuration of atoms (eg obtained from diffraction) this raises questions about the influence of thermal motion on NMR spectra, even if it is thought that there are no specific motional processes, such as exchange, involved.

Dumez and Pickard (66) have examined two ways of including motional effects: by averaging NMR parameters over snapshots taken from molecular dynamics simulations, and by averaging over vibrational modes (as previously used by Rossano et al(67) to study the effects of temperature on $^{17}$O and $^{25}$Mg NMR parameters in MgO). They found the effects of zero-point motion to be significant as well the influence of thermal effects on shielding anisotropies. An extreme example of the effect of temperature on NMR parameters is the case of silsesquioxanes (68). Zero Kelvin simulations strongly overestimate the observed room temperature shielding anisotropies of the $^{29}$Si and $^{13}$C sites. Good agreement between computation and experiment was obtained by averaging the computed NMR parameters over several orientations of the methyl and vinyl
groups. In some cases it may be possible to quantify the effect of temperature experimentally. Webber et al\cite{69} measured the change in $^1$H and $^{13}$C chemical shifts in the range 348 K to 248 K (by simply varying the temperature of the gas used inside the NMR probe). By extrapolating the results to 0K the change in $^1$H shift for the hydroxyl protons with respect to room temperature was 0.5ppm. The change in the C-H $^1$H shifts over the same range was less than 0.1ppm. The experimental shifts extrapolated to 0K were found to be in better agreement with first-principles calculation those those records at room temperature.

### 4.3 Experimental Design

The ability to predict NMR observables allows the experimentalist to examine the feasibility of a particular NMR experiment, or optimise its setup (of course this implies that the experimentalist should trust the accuracy of the calculations!). One such area is the measurement of J-coupling in condensed phases. Current experiments can hope to observe values of J in organic compounds that are above about 5Hz. There is little empirical knowledge about magnitude of J couplings in solids, and so calculations have been used to identify systems with measurable couplings. An initial application of the planewave/pseudopotential approach for computing J-couplings in solids\cite{70} showed that calculations at the PBE level gave values for $^{15}$N-$^{15}$N J-couplings across hydrogen bonds in very good agreement with experimental measurements (typically within the experimental errors). The same study predicted that $^{13}$C-$^{17}$O and $^{15}$N-$^{17}$O J-couplings should be of sufficient magnitude to be observed experimentally. This prompted new experimental work on labelled samples of glycine.HCl and uracil. Further calculations were required to interpret the data resulting in the first experimental determination of the biologically significant $^{13}$C-$^{17}$O, $^{17}$O-$^{17}$O and $^{15}$N-$^{17}$O J-couplings in the solid-state\cite{71}.

![Figure 9: Calculated and Experimental J couplings in the crystalline form of Uracil](image)

### 4.4 Improving First-principles methodologies

Finally, one can look at the situation in the reverse direction and ask how NMR spectroscopy can contribute to the development of electronic structure methods. For a given crystal structure solid-state NMR experiments provide range of tensor properties for each atomic site. Reproduc-
ing this data is a strict test of any first-principles methodology. In our experience, for a given geometry, both LDA and common GGA functionals (PBE, Wu-Cohen, PBEsol) give a very similar description of NMR parameters. Usually the agreement with experiment is reasonably good - a rough rule of thumb is that errors in the chemical shift are within 2-3% of the typical shift range for that element. There are, however, some notable exceptions: Several groups have shown\(^{(56; 72)}\) that while present functionals can predict the trends in \(^{19}\)F chemical shifts, a graph of experimental against calculated shifts has slope significantly less than 1. Another example is the calculation of \(^{17}\)O chemical shifts\(^{(73)}\) in calcium oxide and calcium aluminosilicates. There are significant errors in the \(^{17}\)O shifts which arise due to the failure of GGA-PBE to treat the unoccupied Ca 3d states correctly. In Ref.\(^{(73)}\) it was found that a simple empirical adjustment of the Ca 3d levels via the pseudopotential was sufficient to bring the \(^{17}\)O chemical shifts into good agreement with experiment. However, in both cases it is clear that current GGAs do not describe all of the relevant physics. The converse approach to computing NMR parameters provides an easy route to including exact-exchange in the calculation of magnetic shielding, and it will be interesting to see if this can improve the treatment of these known difficult cases.

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References

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